PC10910US

Appln. No.: 10/593,730

Amendment Dated March 16, 2010

Reply to Office Action of December 28, 2009

<u>Amendments to the Claims:</u> This listing of claims will replace all prior versions, and listings, of claims in the application

Listing of Claims:

1.-11. (Canceled)

12. (Currently Amended) Method for calculating the lateral force in a motor vehicle with an electromechanical or electrohydraulic steering system, the method comprising:

recording a steering rod force of the vehicle;

calculating a total restoring torque from the steering rod force by a calculation unit of the vehicle, with the said total restoring torque comprising a restoring torque generated by lateral force and other restoring torques;

quantitatively determining, by the calculation unit of the vehicle, the other restoring torques based on measured values;

subtracting the other restoring torques from the total restoring torque for determining the restoring torque generated by the lateral force by the calculation unit of the vehicle; and determining the lateral force from the restoring torque generated by the lateral force by the calculation unit of the vehicle.

- 13. (Previously Presented) Method in accordance with claim 12, wherein a transmission ratio between the steering rod force and the total restoring torque is included in the determination of the lateral force.
- 14. (Previously Presented) Method in accordance with claim 13, wherein the transmission ratio is responsive to a steering angle.
- 15. (Previously Presented) Method in accordance with claim 12, wherein a kingpin inclination, a caster angle or a combination thereof is included in the determination of the lateral force.
- 16. (Previously Presented) Method in accordance with claim 12, wherein the other restoring torques comprise one or more of a restoring torque generated by rolling resistance, a brake force, a driving power, and a vertical force.

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17. (Previously Presented) Method in accordance with claim 12, wherein the steering rod force is detected as a force that acts the left and right steering tie rods or as a total steering rod force.

- 18. (Previously Presented) Method in accordance with claim 17, wherein the total steering rod force is calculated from a steering torque generated by the driver, a steering amplification, and a steering ratio.
- 19. (Previously Presented) Method in accordance with claim 18, wherein a steeringangle-responsive steering ratio enters into the calculation of the steering rod force.
- 20. (Previously Presented) Method in accordance with claim 17, wherein the total steering rod force is determined from the motor current and/or the motor position of one or more electric motors of the electromechanical or electrohydraulic steering system.
- 21. (Previously Presented) Method in accordance with claim 12, wherein a sideslip angle is determined from the determined lateral force.
- 22. (Previously Presented) Method in accordance with claim 12, wherein a coefficient of friction is determined from the determined lateral force.
- 23. (New) Method in accordance with claim 12 further comprising the step of outputting the lateral force to a dynamic control system of the vehicle that is configured to check and limit yaw movements of the vehicle based upon the lateral force.